

Abstract of Disclosure

A pre-crash sensing system is coupled to a countermeasure system that has at least a first countermeasure and a second countermeasure. The pre-crash sensing system has a vision system (26) that generates an object size signal and an object distance signal. A controller (12) is coupled to the vision system (26) and deploys either the first countermeasure or first and second countermeasures in response to the object distance and object size.